## 

# HA400 HA900 HA401 HA901



## **General Description**

The HA series are digital PID controllers with a high speed sampling time of 25 ms (0.025 sec) with high-resolution thermocouple, RTD or current voltage input, supplied with parameters settable in 1/100 sec.

A difference between HA400/900 and HA401/901 is in the autotuning. If the process is less than 30 seconds to setpoint, the HA400/900 is best suited with factory default values pre-set for fast process.

Applications in RTP (Rapid Thermal Process), RTA (Rapid Thermal Anneal) and temperature control of semiconductor manufacturing can be controlled by the HA series. The high speed sampling function also makes it suitable for other applications requiring fast control such as pressure or flow rate.

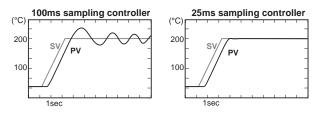


## Features

- ☆ Ultra High Speed Sampling 0.025 sec
- ☆ Two Channels in One Controller
- ☆ Ramp / Soak Program Control
- ☆ Cascade Control
- ☆ Power Feed Forward Function
- ☆ Communications

## Ultra High Speed Sampling 0.025 sec

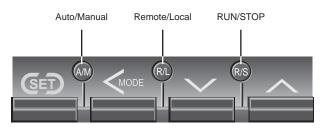
The HA series digital controller supplies feedback control 40 times in one second. It makes the HA series suitable for any application requiring fast control response and high accuracy. The PID parameters can be set in 1/100 unit which supports extremely fast and accurate control by the HA series.



## Direct Function keys

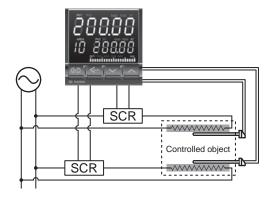
Direct function keys are marked for Auto/Manual, Remote /Local, and Run/Stop switching to eliminate error when entering changing patterns.

Used and Unused of each function key is also possible.



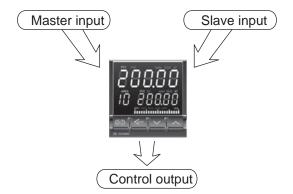
## Two Channels in One Controller

Dual loop control can be performed with a single controller. All loops operate at 0.025ms sampling time.



### Cascade Control in One Controller

Cascade control can be performed with a single controller. Input type can be specified independently for each channel.

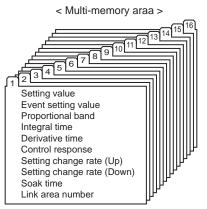


## Features

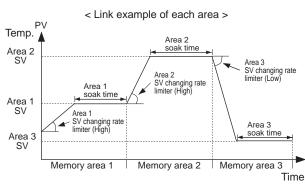
### Ramp / Soak Program Control

The HA Series high speed temperature controller has Multi-memory Area function which stores up to 16 sets of control parameters.

Parameters stored in each memory area are the control set value, event set value, PID values, control response, ramp-to-setpoint UP and DOWN, soak time, and link area number.



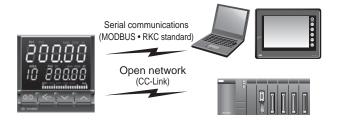
Up to 32-segment ramp/soak control is available by using the memory area function (ramp-to-set point UP and DOWN, soak time, link area number).



Communications

(Optional)

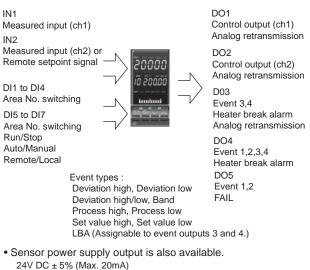
The HA Series incorporates a maximum of two communication ports. The communication method can be selected from serial communication (RS-485, RS-422A, RS-232C) and Open network (DeviceNet, Profibus, CC-Link).



## Numerous Inputs and Outputs

A maximum of two measuring inputs (one input can be used as a remote setpoint signal) and seven event inputs can be specified. A maximum of five outputs can be specified, and various output functions (control output, analog retransmission, event up to 4) can be allocated in output logic operation.

• Available inputs and outputs depend on the specifications.



24V DC ± 5% (Max. 20mA) • Output from OUT3.

• When sensor power supply output is specified, OUT4 and OUT5 can not be added.

## Suitable for Various Process Control

Using industry standard DC inputs (current and voltage), the HA Series can be used in process control applications including pressure, flow rate and levels.

## Autotuning

The Autotuning used on HA400/900 is suitable for a control system with a fast response. PID values can also be manually adjusted so that they may be further optimized for the processes. Just for your information, this Autotuning is performs well for

Just for your information, this Autotuning is performs well for control systems in which temperature rises up to the set point in 30 seconds or faster. If the application is slower (e.g. 5 minutes to reach the set point), HA401/901 are recommended.

## Specifications

### Input

Number of inputs 2 points (IN1 to IN2) Isolated between each channel •2nd input (IN2) can be used as a remote input Cascade connection available Input Universal input a) Low voltage input group Thermocouple : K, J, R, S, B, E, T, N (JIS/IEC) PLII (NBS), W5Re/W26Re (ASTM) •Influence of external resistance : Approx.  $0.25 \mu V/\Omega$ •Input break action : Up-scale / Down-scale (Selectable) RTD : Pt100 (JIS/IEC), JPt100 (JIS) Influence of input lead resistance : Approx. 0.01[°C/Ω] of reading •Maximum 10Ω per wire • Input break action : Up-scale Low voltage : 0 to 1V DC, 0 to 100mV DC, 0 to 10mV DC Input break action : Up-scale / Down-scale (Selectable)
 Current : 4 to 20mA DC, 0 to 20mA DC Input break action : Uncertain (indicates a value around 0mA) b) High voltage input group High voltage : 0 to 5V DC, 1 to 5V DC, 0 to 10V DC Input break action : Uncertain (indicates a value around 0V) Sampling Time 0.025 sec Input Digital Filter 0.01 to 10.00 sec (OFF when 0 is set.) PV Bias -span to +span PV Ratio 0.500 to 1.500 Square Root Extraction Equation : PV = Ö (Input value x PV ratio + PV bias) Low level cut OFF : 0.00 to 25.00% of span Performance Measuring Accuracy a) Thermocouple Type : K, J, T, E, PLII Less than -100°C (-148°F) : ±1.0°C (±1.8°F) -100 to 500°C (-148 to 932°F) : ±0.5°C (±0.9°F) More than 500°C (932°F) : ±(0.1% of Reading + 1 digit) Type : N, S, R, W5Re/W26Re Less than -100°C (-148°F) : ±2.0°C (±3.6°F) -100 to 1000°C (-148 to 1832°F) : ±1.0°C (±1.8°F) More than 1000°C (1832°F) : ±(0.1% of Reading + 1 digit)

#### Type : B Less than 400°C (752°F) : ±70.0°C (±126°F)

400 to 1000°C (752 to 1832°F) : 1.0°C (1.8°F) More than 1000°C (1832°F) :  $\pm$ (0.1% of Reading + 1 digit)

Cold junction temperature compensation error ±1.0°C (1.8°F) [at 23°C±2°C (73.4°F± 3.6°F)]

Within ±1.5°C (± 2.7°F) [Between 0 and 50°C (14 to 122°F)] b) RTD

Less than 200°C (392°F) : ±0.2°C (±0.4°F) More than 200°C (392°F) : ±(0.1% of Reading + 1 digit)

c) DC voltage and DC current

#### ±(0.1% of span)

#### Insulation Resistance

More than 20M $\Omega$  (500V DC) between measured terminals and ground More than  $20M\Omega$  (500V DC) between power terminals and ground

#### **Dielectric Strength**

1000V AC for one minute between measured terminals and ground 1500V AC for one minute between power terminals and ground

## Control

#### Control Method

- a) Brilliant PID control with enhanced autotuning.
- Available for reverse and direct action. b) Position proportioning control.

a) or b) is selectable.

#### Major Setting Range Set value

Proportional band :

- input) Integral time :
- Derivative time :

Control response : Output limiter :

Memory area

0.00 to 360.00sec. or 0.0 to 3600.0sec. (selectable) 0.00 to 360.00sec. or 0.0 to 3600.0sec. (selectable) Slow, Medium, Fast -5.0 to +105.0% (High/Low individual setting) Output change rate limiter :0.0 to 100.0%/sec. (Up/Down individual setting) Proportional cycle time : 0.1 to 100.0 sec. 16 sets

0 to input span (Temperature input)

0.0 to 1000.0% of span (Voltage, Current

Motor Valve Control (position proportioning control type only)

Input resistance (feedback resistance) :  $135\Omega$  as standard POS sampling cycle : 0.075 sec. 0.1 to 10.0% (output), resolution 0.1%

Same as input range.

- Neutral zone : Output : Relav output Motor rotating speed : Suitable for ??? to ??? sec. (full open to full close)
- · When motor valve control is used, neither heater break alarm nor power feed forward function is available

#### Output Ξ

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Main Output					
Number of output :	Up to 3 points (OUT1 to OUT3)				
Output function :	OUT1, 2 : Control output OUT3 : Event output or analog retrans-				
0.4.44	mission output (Optional)				
Output type :	Relay output : Form A contact, 250V AC 3A (resistive load) Voltage pulse output : 0/12V DC (Load resistance : More than 600Ω) Current output : 4 to 20mA DC, 0 to 20mA DC (Load resistance : Less than 600Ω) Continuous voltage output : 0 to 5V DC, 1 to 5V DC, 0 to 10V DC (Load resistance : More than 1kΩ) SSR (Triac) output (Rated current : 0.4A)				
Sub Output (Optional)					
Number of output : Up to 2 points (OUT4, OUT5)					
Output function : Output type :	Event output (Optional) Relay output : Form A contact, 250V AC 1A (resistive load)				
Sensor Power Supply Ou 24V DC ± 5% (Max. 20r • Output from OUT3. • When sensor power s OUT4 and OUT5 can r	nA) upply output is specified,				
Event (Alarm) Output (Optional)					
Number of Event Output Up to 4 points (Event 1					
Alarms					
Туре :	Deviation High, Low, High/Low, Band, Process High, Low Set value High, Low				
Differential gap :	0 to input span				

neater break Alarini (FOI	
CT type :	CTL-6-P-N(30A), CTL-12-S56-10L-N(100A)
Display range :	0.0 to 100.0A
Accuracy :	$\pm$ 5% of input value or $\pm$ 2A (whichever is larger)
Control Loop Break Alar	<b>m</b> (LBA)
LBA time setting :	0.1 to 7200 sec. (OFF by setting zero)
LBA deadband :	0 to input span
<i>Output</i> Assignable to main outp	out (OUT3) or sub output (OUT4 to 5).

#### Other Functions

HOLD action (Valid for deviation/band/PV alarms only) Selection of event action for input abnormality

Heater Break Alarm (For single phase)

## Specifications

## Non-isolated Remote Setpoint Input

(Optional)

#### · Only available in a 1 channel control type.

Input

a) 0 to 1V DC, 0 to 100mV DC, 0 to 10mV DC b) 0 to 5V DC, 1 to 5V DC, 0 to 10V DC c) 4 to 20mA DC, 0 to 20mA DC

Accuracy

#### 0.1% of span

### **Event Input**

#### (Optional)

Number of Inputs Up to 7 points

#### Input Rating

Non-voltage contact input

#### Functions

- a) Memory area selection
- b) Run/Stop switching
- c) Remote/Local switching d) Auto/Manual switching

#### · Event input logic selection functional allocation table

	DI1	DI2	DI3	DI4	DI5	DI6	DI7
1	Me		rea sele o 16)	ction	Area set	Run/Stop	Auto/Manual
2	Me		rea sele o 16)	ction	Area set	Run/Stop	Remote/Local
3	3 Memory area selection (1 to 16)				Area set	Remote/Local	Auto/Manual
4	Memory	y area so (1 to 8)	election	Area set	Run/Stop	Remote/Local	Auto/Manual
5	Memory	y area so (1 to 8)	election	Area set	Remote/Local		
6	Memory	y area se (1 to 8)	election	Area set	Auto/Manual		

### Analog Retransmission Output (Optional)

#### Number of Outputs

Up to 3 points • Functions are assignable to OUT1 to OUT3.

#### Output types

a) Measured value (PV)

b) Deviation (DV)

c) Set value (SV)d) Manipulated output value (MV)

### Communications

(Optional)

Number of communications : 2 points					
Communication method :	COM1: RS-485, RS-232C COM2: RS-232C, RS-485, RS-422A CC-Link				
Communication speed :	2400, 9600, 19200, 38400 BPS				
Protocol :	ANSI X3.28(1976) 2.5 A4 MODBUS				
<i>Bit format</i> Start bit : Data bit : Parity bit : Stop bit :	1 7 or 8 •For MODBUS 8 bit only Without, Odd or Even 1 or 2				
Communication code :	ASCII(JIS) 7-bit code				
Maximum connection :	RS-485, RS-422A : 31 ( Address can be set from 0 to 99.) RS-232C : 1				

## Waterproof/Dustproof

(Optional)

Waterproof/dustproof protection: IP65

·Waterproof/dustproof protection only effective from the front in panel mounted installations.

### **General Specifications**

Supply Voltage	
	AC (Including supply voltage variation)
	ng : 100 to 240V AC] (50/60Hz common)
	4V AC (Including supply voltage variation)
[Rati	ng : 24V AC] (50/60Hz common)
c) 21.6 to 26.4	4V DC (Ripple rate 10% p-p or less) [Rating:24VDC]
Power Consum	ption
HA400 :	Less than 22.5VA for AC type (at 240V AC)
	Less than 15.0VA for 24V AC type
	Less than 430mA for 24V DC type
HA900 :	Less than 24.0VA for AC type (at 240V AC)
	Less than 16.0VA for 24V AC type
	Less than 470mA for 24V DC type
Power Failure E	
	by power failure shorter than 20msec, otherwise reset to e. (HOT or COLD start is selectable.)
Self-Diagnostic	Function
CPU power cl check, etc	heck, Adjustment data check, EEPROM check, RAM
Operating Envi	ronments : -10 to 50°C [14 to 122°F]
	5 to 95% RH.
	Absolute humidity : MAX. W.C 29g/m <sup>3</sup> dry air at 101.3kPa.
Memory Backu	p : Backed up by non-volatile memory.
	Number of writing : Approx. 100,000 times
Net Weight	
HA400 :	Approx. 360g
HA900 :	Approx. 460g
External Dimen	sions (W x H x D)
HA400 :	48 x 96 x 100mm
HA900 :	96 x 96 x 100mm

### Compliance with Standards

#### • CE Mark

• UL/cUL Recognized RCM Mark



· Event output logic selection functional allocation table

OUT1 OUT2 OUT3 OUT4 OUT5							
1         CH1 control HBA1 (Energized) output         Event3 (Energized) HBA2 (Energized)         Event3 (Energized) Event4 (Energized)         Event2 (Energized)         Event1 (Energized)							
2 CH1 control HBA1 (De-energized) Event3 (De-energized) output HBA2 (De-energized) Event4 (De-energized) Event2 (De-energized) Event1 (De-energized)							
3 CH1 control Event3 (Energized) output HBA1 (Energized) HBA2 (Energized) HBA2 (Energized) HBA2 (Energized)							
4 CH1 control Event3 (De-nergized) output HBA1 (De-nergized) HBA2 (De-nergized) HBA2 (De-nergized) HBA2 (De-nergized) FAIL (De-nergized)							
5 CH1 control CH2 control output Event4 (Energized) Event3 (Energized)							
6 CH1 control CH2 control output Event4 (De-energized) Event3 (De-energized) Event1 (De-energized) Event2 (De-							
7 CH1 control CH2 control output Event3 (Energized) Event4 (Energized) HBA1 (Energized) HBA1 (Energized) HBA2 (Energized) Event2 (Energized) Event1 (Energized)							
8 CH1 control CH2 control output Event3 (De-nergized) Event4 (De-nergized) Event2 (De-nergized) HBA1 (De-nergized) Event2 (De-energized) Event1 (De-energized) HBA2 (De-energized)							
CH1 control CH1 control 10 output (OPEN) (CLOSE) HBA2 (Energized) HBA1 (Energized) HBA2 (Energized) HBA2 (Energized) HBA2 (Energized) Event4 (Energized) HBA2 (Energized) Event2 (Energized) Event4							
CH1 control CH1 control output 11 output (CPEN) (CLOSE) HBA2 (De-nergized) Event4 (De-nergized) Event2 (De-energized) Event1 (De-energized) Event1 (De-energized) Event1 (De-energized)							
CH1 control         Event4 (Energized)         Event3 (Energized)         Event3 (Energized)           12         Output         HBA2 (Energized)         HBA1 (Energized)         Event2 (Energized)							
An output logic becomes OR output when two or more output functions are assigned to one output.							

\* When three analog outputs are selected, tha analog outputs are automatically assigned to OUT1 through OUT3 and it has priority over the output logic selection.

## Model and Suffix Code

### 1 channel control type

Specifications		Model and Suffix Coo	le										
Model	HA400 (48 x 96mm 1/8 DIN size) HA900 (96 x 96mm 1/4 DIN size) HA401 (48 x 96mm 1/8 DIN size) HA901 (96 x 96mm 1/4 DIN size)			-□*		□-	-□				-□/	´□ ⁄	1□
Input (IN1 : No 1 input) Non isolated type remote set value	See Input and Range code table Not supplied See Remote input code table												
1 3 Output 1 (Main output)	Relay contact output Voltage pulse output: 0/12V DC DC voltage: 0 to 5V DC voltage: 0 to 10V DC voltage: 1 to 5V DC current: 0 to 20mA DC current: 4 to 20mA SSR (Triac) output	M V 4 5 6 7 8 T											
1 3 Output 2 (Main output) * Not isolated from OUT1.	No output from OUT2 Relay contact output Voltage pulse output : 0/12V DC DC voltage : 0 to 5V DC voltage : 0 to 10V DC voltage : 1 to 5V DC current : 0 to 20mA DC current : 4 to 20mA SSR (Triac) output		N V 4 5 6 7 8 T										
Power supply	24V AC/DC 100 to 240V AC			3 4									
2 3 Output 3 (Main output)	No output from OUT3NRelay contact outputMVoltage pulse output: 0/12V DCVDC voltage: 0 to 5V4DC voltage: 0 to 10V5DC voltage: 1 to 5V6DC current: 0 to 20mA7DC current: 4 to 20mA8SSR (Triac) outputTSensor power supply output (Output 4 and 5 can not added)P												
Output 4, 5 <sup>2</sup> (OUT4, 5 : Sub output)	No outputs from OUT4 and OUT5NOUT4 : Relay contact output, No output from OUT51OUT4 and OUT5 : Relay contact output2												
Event input 1 to 5	Not supplied     N       Event input : 5 points (DI 1 to DI5)     1												
CT input, Power feed forward (PFF) input, Feedback resistance	Not supplied       N         CT input 1 point (CTL-6-P-N)       P         CT input 2 points (CTL-12-S56-10L-N)       S         CT input 2 points (CTL-6-P-N)       T         CT input 2 points (CTL-6-P-N)       U         PFF input (Within transformer 100 to 120V AC type)       1         PFF input (Within transformer 200 to 240V AC type)       2         CT input 1 point (CTL-6-P-N) + PFF input (Within transformer 100 to 120V AC type)       2         CT input 1 point (CTL-6-P-N) + PFF input (Within transformer 200 to 240V AC type)       4         CT input 1 point (CTL-12-S56-10L-N) + PFF input (Within transformer 100 to 120V AC type)       5         CT input 1 point (CTL-12-S56-10L-N) + PFF input (Within transformer 100 to 120V AC type)       5         CT input 1 point (CTL-12-S56-10L-N) + PFF input (Within transformer 200 to 240V AC type)       6         Feedback resistance input       F       6												
Communication 1 or Event input 6 to 7	Not supplied         N           RS-232C (ANSI/RKC standard)         1           RS-485 (ANSI/RKC standard)         5           RS-485 (MODBUS)         6           RS-232C (MODBUS)         8           Event input : DI6 and DI7         D												
Communication 2	Not supplied RS-232C (ANSI/RKC standard) RS-422A (ANSI/RKC standard) RS-485 (ANSI/RKC standard) RS-485 (MODBUS) RS-422A (MODBUS) RS-232C (MODBUS)							N 1 4 5 6 7 8 C					
	CC-Link Not supplied Waterproof/Dustproof protection												_
Waterproof/Dustproof	Not supplied										N 1	N	

<sup>1</sup> Only OUT1 can be used for control outputs. (Only OUT1 and OUT2 can be used for position proportioning control.)
 <sup>2</sup> Event (alarm) outputs, heater break alarm outputs are assignable to OUT3 - OUT5.
 <sup>3</sup> Analog output (PV, SV, etc) are assignable to OUT1 - OUT3.

Caution

• If two isolated analog outputs are required, use OUT1 (or OUT2) and OUT3. OUT1 and OUT2 are not isolated.

To use as a position proportioning controller, two or more outputs must be supplied.
If heater break alarm is assigned to event function, current transformer (sold separately) is required.

#### Autotuning

The Autotuning used on HA400/900 is suitable for a control system with a fast response. PID values can also be manually adjusted so that they may be further optimized for the processes.

Just for your information, this Autotuning is performs well for control systems in which temperature rises up to the set point in 30 seconds or faster. If the application is slower (e.g. 5 minutes to reach the set point), HA401/901 are recommended.

## Model and Suffix Code

### 2 channel control type

Specifications		Model and Suffix Cod	е									_
Model	HA400 (48 x 96mm 1/8 DIN size) HA900 (96 x 96mm 1/4 DIN size) HA401 (48 x 96mm 1/8 DIN size) HA901 (96 x 96mm 1/4 DIN size)		□-	-□*[		]—[			□-	-0/	´□/[	
Input 1 (IN1 : No 1 input) Input 2 (IN2 : No 2 input)	See Input and Range code table See Input and Range code table					_	_					
1 3 Output 1 (Main output)	Relay contact output Voltage pulse output : 0/12V DC DC voltage : 0 to 5V DC voltage : 0 to 10V DC voltage : 1 to 5V DC current : 0 to 20mA DC current : 4 to 20mA SSR (Triac) output	M V 4 5 6 7 8 T										
1 3 Output 2 (Main output) * Not isolated from OUT1.	No output from OUT2 Relay contact output Voltage pulse output : 0/12V DC DC voltage : 0 to 5V DC voltage : 0 to 10V DC voltage : 1 to 5V DC current : 0 to 20mA DC current : 4 to 20mA SSR (Triac) output		N V 4 5 6 7 8 T									
Power supply	24V AC/DC 100 to 240V AC			3 4								
2 3 Output 3 (Main output)	No output from OUT3 Relay contact output Voltage pulse output : 0/12V DC DC voltage : 0 to 5V DC voltage : 0 to 10V DC voltage : 1 to 5V DC current : 0 to 20mA DC current : 4 to 20mA SSR (Triac) output Sensor power supply output (Output 4 ar	nd 5 can not added)			/ 							
Output 4, 5 2 (OUT4, 5 : Sub output)	No outputs from OUT4 and OUT5 OUT4 : Relay contact output, No output OUT4 and OUT5 : Relay contact output	rom OUT5			N 1 2							
Event input 1 to 5	Not supplied Event input : 5 points (DI 1 to DI5)					N 1						
CT input, Power feed forward (PFF) input, Feedback resistance	Not suppliedNCT input 1 point (CTL-6-P-N)PCT input 1 point (CTL-12-S56-10L-N)SCT input 2 points (CTL-6-P-N)TCT input 2 points (CTL-12-S56-10L-N)TCT input 2 points (CTL-6-P-N)UPFF input (Within transformer 100 to 120V AC type)1PFF input (Within transformer 200 to 240V AC type)2CT input 1 point (CTL-6-P-N) + PFF input (Within transformer 100 to 120V AC type)3CT input 1 point (CTL-6-P-N) + PFF input (Within transformer 200 to 240V AC type)4CT input 1 point (CTL-12-S56-10L-N) + PFF input (Within transformer 100 to 120V AC type)5CT input 1 point (CTL-12-S56-10L-N) + PFF input (Within transformer 200 to 240V AC type)5Feedback resistance inputF											
Communication 1 or Event input 6 to 7	Not supplied RS-232C (ANSI/RKC standard) RS-485 (ANSI/RKC standard) RS-485 (MODBUS) RS-232C (MODBUS) Event input : DI6 and DI7							N 1 5 6 8 D				
Communication 2	Not supplied RS-232C (ANSI/RKC standard) RS-422A (ANSI/RKC standard) RS-485 (ANSI/RKC standard) RS-485 (MODBUS) RS-422A (MODBUS) RS-422C (MODBUS) CC-Link								N 1 4 5 6 7 8 C			
Waterproof/Dustproof	Not supplied Waterproof/Dustproof protection									N 1		
Body color	White Black										N A	
Instrument version	Version symbol											Y

<sup>1</sup> Only OUT1 and OUT2 can be used for control outputs.

<sup>2</sup> Event (alarm) outputs, heater break alarm outputs are assignable to OUT3 - OUT5. <sup>3</sup> Analog output (PV, SV, etc) are assignable to OUT1 - OUT3.

#### Caution

• If two isolated analog outputs are required, use OUT1 (or OUT2) and OUT3. OUT1 and OUT2 are not isolated.

• To use as a position proportioning controller, two or more outputs must be supplied. • If heater break alarm is assigned to event function, current transformer (sold separately) is required.

Autotuning The Autotuning used on HA400/900 is suitable for a control system with a fast response. PID values can also be manually adjusted so that they may be further optimized for the processes.

Just for your information, this Autotuning is performs well for control systems in which temperature rises up to the set point in 30 seconds or faster. If the application is slower (e.g. 5 minutes to reach the set point), HA401/901 are recommended.

#### Range and Input Table

Thermocouple, RTD, Low voltage and Current group
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Thermocoupie,	KID, L	Jw voltage and Current	group				
Input	Code	Ra	Resolution				
K	К	-200 - 1372°C	-328 - 2501°F				
J	J	-200 - 1200°C	-328 – 2192°F				
Т	Т	-200 - 400°C	-328 – 752°F				
E	E	-200 - 1000°C	-328 - 1832°F				
PLII	A	0 - 1390°C	32 – 2534°F	1°C, 0.1°C, 1°F, 0.1°F			
N	N	0 - 1300°C	32 – 2372°F	(Selectable)			
S	S	-50 - 1768°C	-58 - 3214°F				
R	R	-50 – 1768°C	-58 – 3214°F				
W5Re/W26Re	W	0 - 2300°C	32 – 4172°F				
В	В	0 - 1800°C	32 - 3272°F				
Pt100 (3 wire)	D	-200 - 850°C	-328 - 1562°F	110 0 110 0 0110			
JPt100 (3 wire)		-200 - 600°C	-328 - 1112°F	1°C, 0.1°C, 0.01°C			
Pt100 (4 wire)		-200 - 850°C	-328 - 1562°F	1°F, 0.1°F, 0.01°F			
JPt100 (4 wire)	С	-200 - 600°C	-328 - 1112°F	(Selectable)			
0 - 10mV DC							
0-100mV DC	3						
0 - 1V DC	1	-19999 — (Drogram		1, 0.1, 0.01, 0.001, 0.0001			
0 - 20mA DC	8	(Program	mable)	(Programmable)			
4 - 20mA DC	0						
High voltage group							
0 - 5V DC		-19999 —	99999	1, 0.1, 0.01, 0.001, 0.0001			
0 - 10V DC 1 - 5V DC	6	(Program		(Programmable)			
		I					

#### Remote Signal Code Table

Not isolated from the No.1 input [IN1]

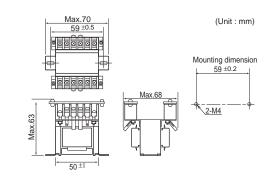
Input type			
	0 - 10mV DC		
Low voltage group	0 - 100mV DC	G	
	0 - 1V DC		
	0 - 5V DC		
High voltage group	0 - 10V DC	V	
	1 - 5V DC		
Current group	0 – 20mA DC	v	
Current group	4 – 20mA DC	I I	

#### Power Feedback Transformer (for Power Feed Forward Input)

• Supplied when power feed forward function is specified.

When ordering transformer for replacement, please specify one of the following model codes :

Specification	Model Code
100 to 120V AC type	PFT - 01
200 to 240V AC type	PFT - 02

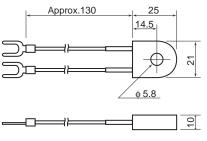


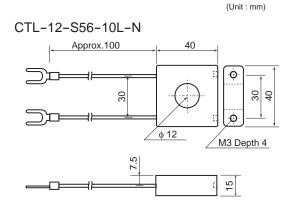
#### Current Transformer (CT) J

#### Sold separately.

Name	Range	Model Code				
Current transformer for	0 — 30A	CTL-6-P-N				
heater break alarm	0-100A	CTL-12-S56-10L-N				



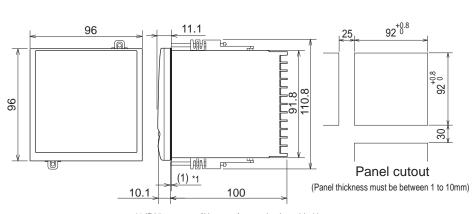


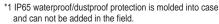


## **External Dimensions and Rear Terminals**

## HA900, HA901

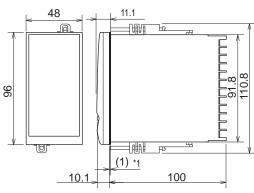
1 🕀	49 🚱	37 🕀	25 💮	13 💮
2	50 🕀	38 🕀	26 🕀	14 🕀
3	51 🕀	39 🕀	27	15
4 🕀	52 🕀	40	28	16
5	53 🕀	41 🕀	29 🕀	17 🕀
6 🕀	54 🕀	42 🕀	30 🕀	18 🕀
7 🕀	55 🕀	43 🕀	31	19 🕀
8 🕀	56 🕀	44 🕀	32	20
9 🕀	57 🕀	45 🕀	33 🕀	21 🕀
10 🕀	58 🕀	46 🕀	34 🕀	22 🕀
11 🕀	59 🕀	47 🕀	35 💮	23 🕀
12 🕀	60 🕀	48 🕀	36 🕀	24

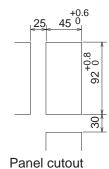




## HA400, HA401

1	A	25	$\bigcirc$	13	
2	Ð	26	•	14	
3	Ð	27	0	15	•
4	⊕	28	0	16	$\Theta$
5	$\oplus$	29	0	17	$\Theta$
6	€	30	0	18	$\Theta$
7	Ð	31	0	19	$\Theta$
8	€	32	$\oplus$	20	$\odot$
9	€	33	0	21	$\odot$
10	€	34	$\oplus$	22	$\odot$
11	€	35	$\odot$	23	$\odot$
12	€	36	$\odot$	24	$\odot$





Unit : mm

(Panel thickness must be between 1 to 10mm)

\*1 IP65 waterproof/dustproof protection is molded into case and can not be added in the field.

No	Desa	iption		No		No	Description		1Г	No	Description		
1		Power supply	49 50	-	-	25 26	SG - T (A) -	SG SG T/R (A) SD	* Communication		13 14	SG SG (A) COM (B)	(A) Communication 1 (1)RS-485 (2)RS-232C
3	NO Relay contact	* Output 5 (OUT5)	51	39		27	т(B) -	(2) T/R (B) (3)	(1) RS-422A		15	T/R (B)RD017	(B) Event input 6 to 7 Non-voltage contact input
4	output	,	52	40		28	— R (A)		(2) RS-485 (3) RS-232C		16	COM (A) OPEN (B) COM (C)	(A) CT1,CT2 input *
5	Relay contact	* Output 4 (OUT4)	53	41		29	(1) R (B)				17	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	(B) Feedback resistance input
6	NO output	o a p a c ( o o c . )	54	42	Not used	30	COM	(-)	*		18		(C) CT1 input + Power feed forward input
7	ר ד + ד ד <del>א</del> סמ	Output 3 (OUT3) * (1) Relay contact output (2) Voltage pulse/Current/	55	43		31	DI1				19	Non isolated type remote input (A) A (B)	(A) 1 channel type
8		(3) SSR (Triac) output (4) Sensor power supply output	56	44		32	012	Non-voltage contact input	Event input 1 to 4		20	+ −	No.1 Input (IN1) + Non-isolated type
9	+	Output 2 (OUT2) * (1) Relay contact output	57	45		33	013				21	No.1 Input (IN 1)	remote input (B) 2 channel type
10		<ul> <li>(2) Voltage pulse/Current/ Voltage output</li> <li>(3) SSR (Triac) output</li> </ul>	58	46		34	014				22	A — No.1 Input (IN 1)	No.1 Input (IN1) + No.2 Input(IN 2)
11	+	Output 1 (OUT1) (1) Relay contact output	59	47		35	Сом	(-) Non-voltage	*		23	│+ B\	(1) Thermocouple (2)-1 RTD (3 or 4 wire)
12	$ \begin{bmatrix} NO \\ 0 \\ -1 \\ (1) \\ (2) \\ (3) \\$	(2) Voltage pulse/Current/ Voltage output (3) SSR (Triac) output	60			36	DI5	contact input	Event input 5	ΙL	24	$\begin{bmatrix} \vdots \\ (1) \\ (2) \\ (2) \\ (2) \\ (2) \\ (2) \\ (3) \\ (1) \\ (2) \\ (2) \\ (2) \\ (3) \\ (3) \\ (2) \\ (3) $	(2)-2 RTD (3 wire) (3) Voltage/Current

\* Functions (A) to (C) and types (1) to (3) must be specified when instrument is ordered as change can not be made in the field.

\* : Option